To: Workshop and Tutorials chair ICRA 2019

As the co-chair of the Computer and Robot Vision Technical Committee of the IEEE Robotics and Automation Society, I wish to express our trong support for the workshop:

Bringing perception-based manipulation to the real world: standardizing robot manipulation learning

The workshop covers several topics related to the interests of members of TC, integration of visual and tactile sensing for interaction with the environment. The proposal identified a set of invited speakers along with participation of key industrial players to join the workshop and participate in the discussion panel. Given its multi-disciplinary nature it is also closely related to the other fields including haptics, perception, learning and control planning and contol. The rationale for the workshop is well thought through and the proposal is well organized.

Darius Burschka

September 24, 2018

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Co-chair RAS TC on Computer and Robot Vision

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