Dear Prof. Haddadin,

The IEEE-RAS TC on Robot Learning is happy to support you workshop proposal "Bringing perception-based manipulation to the real world: standardizing robot manipulation learning". The topic aligns very well with our TC but will be also highly relevant for the broader community, we sincerely recognize the importance of the proposed topic. Both the organizers and the invited speakers are leading researchers in this field.

We wish you all the best with the organization of this exciting workshop!

Jens Kober
Co-chair, IEEE-RAS Technical Committee on Robot Learning