

Deterministic Identification

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Outline



- 2 Main Contributions
- Optimizions and Related Work

4 Main Results

5 Conclusions



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- 2 Main Contributions
- 3 Definitions and Related Work
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Transmission vs. Identification

• Shannon's setting: Bob recover the message

$$i \rightarrow \boxed{\mathsf{Enc}} \stackrel{\mathbf{u}_i}{\longrightarrow} \boxed{\mathsf{noisy channel}} \stackrel{\mathbf{Y}}{\longrightarrow} \boxed{\mathsf{Dec}} \rightarrow \hat{i}$$

• Identification setting: Bob asks if a message was sent or not?





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 $\label{eq:Apps} \begin{array}{l} \textbf{Apps} \rightarrow \text{vehicle-to-X communications, health care, point to} \\ \text{multi-point communication, molecular communication, online} \\ \text{sales, communication complexity, and any event-triggered scenario} \end{array}$



Randomized Identification (RI)¹

- Originally introduced by Ahlswede and Dueck (1989)
- Capacity was established with randomness at encoder
- Encoder employs distribution to select codewords

Remarkable Property

- Reliable identification is possible with code size growth $\sim 2^{2^{nR}}$
- Sharp difference to transmission with code size growth $\sim 2^{nR}$

¹Ahlswede, R. and Dueck, G. "Identification via channels", 1989



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For
$$R=0.01$$
 and $n=821
ightarrow 2^{2^{8.21}}
ightarrow \#$ of atoms in universe

¹Ahlswede, R. and Dueck, G. "Identification via channels", 1989



Deterministic Identification (DI)²

- Encoder uses deterministic mapping for coding
- Code size $\sim 2^{nR}$ for DMC as in transmission paradigm
- Achievable rates higher than transmission

Why deterministic?

- Simpler implementation (random resource not required)
- Suitable for Jamming scenarios
- Suitable for molecular communication ^a

 $\ensuremath{^{\circ}}\xspace{Nakano, et. al, "Molecular communication and networking: Opportunities and challenges", 2012$

²Ahlswede, R. and Cai, N. "Identification without randomization", 1999



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Main Contributions

- We established the DI capacity for three channel models with power constraints:
 - DMC
 - Fast Fading
 - Slow Fading



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 - DMC
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 - Slow Fading
- We show that the optimal code size scales as $\sim 2^{nR}$ for the DMC and as $\sim 2^{n\log(n)R} = n^{nR}$ for the fading channels



Main Contributions

- We established the DI capacity for three channel models with power constraints:
 - DMC
 - Fast Fading
 - Slow Fading
- We show that the optimal code size scales as $\sim 2^{nR}$ for the DMC and as $\sim 2^{n\log(n)R} = n^{nR}$ for the fading channels
- Our analysis combines techniques and ideas from both works, by JáJá^a and Ahlswede^b

^aJa, J.J., "Identification is easier than decoding", 1985
 ^bAhlswede, R. "A method of coding and its application to arbitrarily varying channels", 1980



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Definition (Transmission Code)



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- Code size: $L(n, R) = 2^{nR}$
- **2** Code-word: $u_i \in \mathcal{X}^n$, decoding regions: $\mathcal{D}_i \subset \mathcal{Y}^n$



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- **3** Input constraint: $\frac{1}{n} \sum_{t=1}^{n} \phi(u_{i,t}) \leq A$ with $\phi : \mathcal{X} \to [0, \infty)$
- **(**) Error requirement: $W^n(\mathcal{D}_i | \boldsymbol{u_i}) \geq 1 \epsilon$
- **5** Non-overlapping decoding regions: $\mathcal{D}_i \cap_{\substack{i \neq j \\ i \neq j}} \mathcal{D}_j = \emptyset$



Definition (Achievable Rate)

A rate R is called achievable if for every positive ε and sufficiently large n, there exists an $(L(n, R), n, \varepsilon)$ -code

Definition (Channel Capacity)

 $\mathbb{C}_{\mathcal{T}}(\mathcal{W}) = \sup\{R \,|\, \mathsf{R} \text{ is achievable}\}$



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Definition (Channel Capacity)

$$\mathbb{C}_{\mathcal{T}}(\mathcal{W}) = \sup\{R \,|\, \mathsf{R} ext{ is achievable}\}$$

Theorem (Shannon, 1948)

Transmission capacity of a DMC W for $L(n, R) = 2^{nR}$ is given by $\mathbb{C}_T(W, L) = \max_{p_X} I(X; Y)$





Definition (Ahlswede and Cai, 1999)

A $(L(n, R), n, \lambda_1, \lambda_2)$ -DI code for DMC W is a system $\{(u_i, D_i)\}_{i \in [1:L(n,R)]}$ subject to



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 - **3** Input constraint: $\frac{1}{n} \sum_{t=1}^{n} \phi(u_{i,t}) \leq A$ with $\phi : \mathcal{X} \to [0, \infty)$
 - **④** Error requirement type I: $W^n(\mathcal{D}_i | \boldsymbol{u}_i) > 1 \lambda_1$
 - **5** Error requirement type II: $W^n(\mathcal{D}_i | \boldsymbol{u}_j) \underset{i \neq i}{<} \lambda_2$



Geometry of DI Codes





RI Codes

Ahlswede and Dueck, 1989

Given local randomness at the transmitter, encoder send a random codeword $u_i \sim Q_i$.

Theorem (Ahlswede and Dueck, 1989)

RI capacity of a DMC W for $L(n, R) = 2^{2^{nR}}$ is given by

$$\mathbb{C}_{RI}(\mathcal{W},L) = \max_{p_X} I(X;Y)$$



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DI Capacity of DMC

Theorem

^a Let W be a DMC with distinct rows in channel matrix. Then for $L(n, R) = 2^{nR}$, the DI capacity under input constraint is given by

$$\mathbb{C}_{DI}(\mathcal{W},L) = \max_{p_X : \mathbb{E}\{\phi(X)\} \leq A} H(X)$$

^aarXiv:2010.04239, 2020



DI Capacity of DMC

Theorem (Ahlswede and Dueck, 1989; Ahlswede and Cai, 1999)

For DMC W let $W : \mathcal{X} \to \mathcal{Y}$ be channel matrix with distinct rows. Then for $L(n, R) = 2^{nR}$, the DI capacity is given by

 $\mathbb{C}_{DI}(\mathcal{W}, L) = \log |\mathcal{X}|$

- A proof was not provided
- Consequence of our result with $A = \phi_{max}$

•
$$\mathbb{C}_{DI}(\mathcal{W}, L) = \max_{p_X : \mathbb{E}\{\phi(X)\} \le \phi_{max}} H(X) = H(X) |_{p_X \sim \mathcal{U}(\{1:|\mathcal{X}|\})} = \log |\mathcal{X}|$$



Proof Sketch (Achievability)

Lemma

Let R < H(X) and $\epsilon > 0$. Then, $\exists U^* = \{v_i\}_{i \in M}$ such that

$$2 d_H(\mathbf{v}_i, \mathbf{v}_j) \geq n\epsilon \quad \forall i \neq j$$

$$|\mathcal{M}| \geq 2^{n(R-\theta)}$$

Coding Scheme

• **Enc**: given message $i \in \mathcal{M}$ transmit $x^n = \mathbf{v}_i$

• Dec:
$$\mathcal{D}_j = \{y^n : (\mathbf{v}_j, y^n) \in \mathcal{T}_{\delta}(p_X W)\}$$

Error Analysis

P_{e,1}(i) ≤ 2^{-α₁(δ)n} by standard type class argument
 P_{e,2}(i,j) ≤ 2^{-nα₂(ε,δ)} by conditional type intersection lemma



Proof Sketch (Achievability)

Lemma (Ahlswede, 1980)

Let $W : \mathcal{X} \to \mathcal{Y}$ be a channel matrix of a DMC \mathcal{W} with distinct rows. Then, for every $x^n, x'^n \in \mathcal{T}_{\delta}(p_X)$ with $d(x^n, x'^n) \ge n\epsilon$,

$$\frac{|\mathcal{T}_{\delta}(p_{\boldsymbol{Y}|\boldsymbol{X}}|\boldsymbol{x}^n)\cap\mathcal{T}_{\delta}(p_{\boldsymbol{Y}|\boldsymbol{X}}|\boldsymbol{x}'^n)|}{|\mathcal{T}_{\delta}(p_{\boldsymbol{Y}|\boldsymbol{X}}|\boldsymbol{x}^n)|}\leq e^{-ng(\epsilon)}$$

with $p_{Y|X} \equiv W$, for sufficiently large n and some positive function $g(\epsilon) > 0$ which is independent of n.



Proof Sketch (Converse)

Lemma

Distinct messages have distinct codewords, i.e.,

$$i_1 \neq i_2 \Rightarrow \mathbf{u}_{i_1} \neq \mathbf{u}_{i_2}$$

Proof. If $\boldsymbol{u}_{i_1} = \boldsymbol{u}_{i_2} = x^n$, then

$$P_{e,1}(i_1) + P_{e,2}(i_2,i_1) = W^n(\mathcal{D}_{i_1}^c|x^n) + W^n(\mathcal{D}_{i_1}|x^n) = 1$$



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Further Steps

•
$$2^{nR} \le |\{x^n : n^{-1} \sum_{t=1}^n \phi(x_t) \le A\}|$$

•
$$|\{x^n : n^{-1} \sum_{t=1}^n \phi(x_t) \le A\}| \le 2^{n(\max_{p_X : \mathbb{E}\{\phi(X)\} \le A} H(X) + \alpha_n)}$$

since input subspace is a union of type classes

•
$$R \leq \max_{p_X : \mathbb{E}\{\phi(X)\} \leq A} H(X) + \alpha_n$$
 for $\alpha_n \xrightarrow{n \to \infty} 0$



DI for Gaussian Channel

Theorem

^a Let \mathscr{G} ; $\mathbf{Y} = \mathbf{x} + \mathbf{Z}$ be Gaussian channel with power constraint $\|\mathbf{x}\|^2 \leq nA$ and $\mathbf{Z} \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_Z^2)$. Then for $L(n, R) = 2^{nR}$, DI capacity is given by

 $\mathbb{C}_{DI}(\mathscr{G},L)=\infty$

^aarXiv:2010.04239



Figure 1: DI over Gaussian channel



Proof Sketch.

Proof I

- ullet Dense sphere packing arrangement with radius $\sqrt{\epsilon}$
- Minkowski-Hlawka Theorem guarantees a density $\Delta \geq 2^{-n}$

•
$$2^{nR} = \frac{\operatorname{Vol}\left(\bigcup_{i=1}^{2^{nR}} \mathcal{S}_{\mathbf{u}_{i}}(n,\sqrt{\epsilon})\right)}{\operatorname{Vol}(\mathcal{S}_{\mathbf{u}_{1}}(n,\sqrt{\epsilon}))} = \Delta \cdot \frac{\operatorname{Vol}(\mathcal{S}_{\mathbf{0}}(n,\sqrt{A}))}{\operatorname{Vol}(\mathcal{S}_{\mathbf{u}_{1}}(n,\sqrt{\epsilon}))} \ge 2^{-n} \cdot \left(\frac{A}{\epsilon}\right)^{\frac{n}{2}}$$

• $R \ge \frac{1}{2} \log\left(\frac{A}{\epsilon}\right) - 1 \xrightarrow{\epsilon \to 0} \infty$



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• $R \ge \frac{1}{2} \log\left(\frac{A}{\epsilon}\right) - 1 \xrightarrow{\epsilon \to 0} \infty$

Proof II

 \bullet Apply quantization to approximate ${\mathscr G}$ with a DMC

•
$$H(X^{\Delta}) \approx \frac{1}{2} \log(2\pi e A) - \frac{2}{\sqrt{2\pi A}} \Delta + \log \frac{1}{\Delta}$$

• $R \xrightarrow{\Delta \to 0^+} \infty$



DI for Fading Channel



Definitions

- Fast fading $\rightarrow \mathbf{Y} = \mathbf{G} \circ \mathbf{x} + \mathbf{Z}$ where $\mathbf{G} = (G_t)_{t=1}^{\infty} \stackrel{iid}{\sim} f_G$
- Slow fading $\rightarrow Y_t = Gx_t + Z_t$ where $G \sim f_G$
- Power const. $\rightarrow \|\mathbf{x}\| \leq \sqrt{nA}$, Noise $\rightarrow \mathbf{Z} \stackrel{\textit{iid}}{\sim} \mathcal{N}(0, \sigma_Z^2)$
- $\mathcal{G} \triangleq$ set of fading coefficient values



DI for Fast Fading Channel

Theorem

^a Let \mathscr{G}_{fast} be fast fading channel with positive fading coefficients. Then the DI capacity for $L(n, R) = 2^{n \log(n)R}$ is given by $\frac{1}{4} \leq \mathbb{C}_{DI}(\mathscr{G}_{fast}, L) \leq 1$

^aarXiv:2010.10010



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Corollary (Traditional Scales)

DI capacity in traditional scales is given by

$$\mathbb{C}_{DI}(\mathscr{G}_{fast}, L) = \begin{cases} \infty & \text{for } L(n, R) = 2^{nR} \\ 0 & \text{for } L(n, R) = 2^{2^{nR}} \end{cases}$$

- Standard Gaussian channel is a special case
- To prove lower-bound, we pack sphere of radius $\sqrt{n\epsilon_n} \sim n^{\frac{1}{4}}$, which results in $\sim 2^{\frac{1}{4}n\log(n)}$ codewords



DI for Slow Fading Channel

Theorem

^a Let \mathscr{G}_{slow} be slow fading Gaussian channel. Then DI capacity for $L(n,R)=2^{n\log(n)R}$ is given by

$$\begin{split} & \frac{1}{4} \leq \mathbb{C}_{DI}(\mathscr{G}_{\textit{slow}}, L) \leq 1 & \text{if } 0 \notin \textit{cl}(\mathcal{G}) \\ & \mathbb{C}_{DI}(\mathscr{G}_{\textit{slow}}, L) = 0 & \text{if } 0 \in \textit{cl}(\mathcal{G}) \end{split}$$

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Corollary (Traditional Scales)

$$DI \text{ capacity in traditional scales is given, by} \\ \mathbb{C}_{DI}(\mathscr{G}_{slow}, L) = \begin{cases} 0 & \text{if } 0 \in cl(\mathcal{G}) \\ \infty & \text{if } 0 \notin cl(\mathcal{G}) \end{cases}, \text{ for } L(n, R) = 2^{nR} \\ \mathbb{C}_{DI}(\mathscr{G}_{slow}, L) = 0, \text{ for } L(n, R) = 2^{2^{nR}} \end{cases}$$



Discontinuity of DI Capacity

Binary Symmetric Channel

• For
$$\epsilon < \frac{1}{2}$$
 (arbitrary close to $\frac{1}{2}$): $W = \begin{pmatrix} 1 - \epsilon & \epsilon \\ \epsilon & 1 - \epsilon \end{pmatrix} \Rightarrow$
 $\mathbb{C}_{DI}(BSC) = \log(n_{row}[W]) = \log 2 = 1$

• For $\epsilon = \frac{1}{2}$, it is a pure noise channel, and $W = \begin{pmatrix} 0.5 & 0.5 \\ 0.5 & 0.5 \end{pmatrix} \Rightarrow \mathbb{C}_{DI}(BSC) = \log(n_{row}[W]) = \log 1 = 0$



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Conclusions

• We have determined DI capacity for

- 1 DMC $\rightarrow 2^{nC}$ behavior
- **2** Fading $\rightarrow 2^{n \log(n)C} = n^{nC}$ behavior

As opposed to $2^{2^{nR}}$ for random identification

- Future directions
 - Multi-user scenarios
 - Ø Molecular communication channel (with memory)
 - Sinite block-length regime



Discussion

Thank You!



Π

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ϵ -DI Capacity for DMC

Theorem (Ahlswede et al, 1989; Burnashev, 2000)

For a DMC W with $L(n, R) = 2^{2^{nR}}$, the ϵ -DI Capacity for $\epsilon \in [0, \frac{1}{2})$ are given by

$$\mathbb{C}_{RI}^{\epsilon}(\mathcal{W},L) = \mathbb{C}_{RI}(\mathcal{W},L) = \max_{P_X} I(X;Y)$$

$$\mathbb{C}^{\epsilon}_{DI}(\mathcal{W},L)=\mathbb{C}_{DI}(\mathcal{W},L)=0$$

Theorem (Ahlswede et al, 1989)

 ϵ -DI and ϵ -RI achievable rate with $L(n, R) = 2^{2^{nR}}$ for $\epsilon \geq \frac{1}{2}$ can be made arbitrary large, i.e.,

$$\mathbb{C}^{\epsilon}_{DI}(\mathcal{W},L)=\mathbb{C}^{\epsilon}_{RI}(\mathcal{W},L)=\infty$$

 $\mathsf{Proof} \to \mathsf{Decoder} \ \mathsf{flips} \ \mathsf{a} \ \mathbf{fair} \ \mathbf{coin}$

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ε-DI Capacity for Gaussian Channel

Theorem (Burnashev, 2000)

For a Gaussian channel with $L(n, R) = 2^{2^{nR}}$, the ϵ -DI capacity for $\epsilon \geq \frac{1}{2}$ is given by

$$\mathbb{C}^{\epsilon}_{DI}(\mathscr{G},L) = \mathbb{C}^{\epsilon}_{RI}(\mathscr{G},L) = \infty$$

Theorem (Labidi et al, 2020)

For a Gaussian channel under input constraint $\|\mathbf{x}\|^2 \leq nA$ with $L(n, R) = 2^{2^{nR}}$, the ϵ -DI capacity for $\epsilon \in [0, \frac{1}{2})$ is given by

$$\mathbb{C}^{\epsilon}_{RI}(\mathscr{G},L) = \mathbb{C}_{RI}(\mathscr{G},L) = rac{1}{2}\log\left(1+rac{A}{\sigma^2_Z}
ight)$$



DI for Compound Channel

- $\textcircled{\ } \textbf{Let} \ \mathcal{V} = \{ V(.|.,s) \ : \ s \in \mathcal{S} \}_{|\mathcal{S}| < \infty} \ \text{be a compound channel}$
- Each V(.|., s) induces a partition {X(1|s), ..., X(j_s|s)} of X with

$$x, x' \in \mathcal{X}(.|s) \iff V(.|x,s) = V(.|x',s)$$

• Any RV X taking values in \mathcal{X} induces a RV $\hat{X}(s)$ s.t. $\hat{X}(s) = k \iff X \in \mathcal{X}(k|s)$ for $k \in [1:j_s]$

Theorem (Ahlswede and Cai, 1999)

$$C_{DI}(\mathcal{V}, L) = \max_{X} \min_{s} H(\hat{X}(s)) \quad \text{for } L(n, R) = 2^{nR}$$

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DI for AVC

Theorem (Ahlswede and Cai, 1999)

• Let
$$P \in \mathcal{P}(\mathcal{X})$$
 and $\overline{\overline{\mathcal{A}}}$ be the row-convex closure of \mathcal{A}

then

$$C_{DI}(\mathcal{A}) \geq \max_{\mathcal{P}} \min_{(X,X',Y) \in \mathcal{Q}(\mathcal{P},\mathcal{A})} I(X' \wedge XY)$$



DI Capacity of AVC I

• For every fixed $x \in \mathcal{X}$ define

$$\mathcal{A}_1(x) = \{A(.|x,s) : s \in \mathcal{S}\}$$

as set of PDs on $\mathcal Y$ where $\mathcal A_1 = \{ \mathcal A(.|.,\ s) : s \in \mathcal S \}$

• Define $\overline{A}(x)$ as **convex closure** of $A_1(x)$ i.e. of entries in form

$$\sum_{s\in\tilde{\mathcal{S}}}P(s)A(y|x,s)$$



DI Capacity of AVC II

• Define **row-convex closure** of \mathcal{A} denote by $\overline{\mathcal{A}}$ as follows:

$$\overline{\overline{\mathcal{A}}} = \{(\mathcal{A}(y|x))_{x\in\mathcal{X},y\in\mathcal{Y}}: \mathcal{A}(.|x)\in\overline{\mathcal{A}}(x)\}$$

 $\overline{\overline{\mathcal{A}}}$ has entries of form:

$$\sum_{s\in\tilde{\mathcal{S}}} P(s|x)A(y|x,s)$$

P(s|x) means that coefficient are conditioned on choice of x, i.e., for every different x there would be in general a complete different set of coefficients than that of required for defining entries of $\overline{A}(x)$



DI Codes for Gaussian Channel

Cost Constraints

Average power constraint:

$$\frac{1}{n}\sum_{1}^{n}|x_{t}|^{2}\leq P\iff \|x^{n}\|_{2}\leq \sqrt{nP}$$

2 Peak power constraint:

$$\max_{1\leq t\leq n}|x_t|\leq A\iff \|x^n\|_{\infty}\leq A$$



DI Capacity Results

Theorem (JáJá, 1985)

For Binary Symmetric Channel (BSC) with $\epsilon \neq 0.5$, the DI with rate arbitrarily close to 1 is possible, i.e,

 $\mathbb{C}_{DI}(BSC) = 1$

Theorem (Ahlswede, 1989)

For DMC W with stochastic matrix W, let n_{row} be # of distinct rows in W, then the DI capacity is given by

 $\mathbb{C}_{DI}(\mathcal{W}) = \log\left(n_{row}[\mathcal{W}]\right)$



Geometry of RI Codes

