

Coding and Modulation

A Polar Coding Viewpoint

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Outline

- ▶ **Background**
 - ▶ AWGN channel
 - ▶ Coding and modulation
- ▶ Polar coding and modulation
 - ▶ Direct polarization approach
 - ▶ Multi-level modulation and polar coding
 - ▶ Lattices and polar codes
 - ▶ BICM and polar coding

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The AWGN Channel

The AWGN channel is a continuous-time channel

$$Y(t) = X(t) + N(t)$$

such that the input $X(t)$ is a random process bandlimited to W subject to a power constraint $\overline{X^2(t)} \leq P$, and $N(t)$ is white Gaussian noise with power spectral density $N_0/2$.

Capacity

Shannon's formula gives the capacity of the AWGN channel as

$$C_{[b/s]} = W \log_2(1 + P/WN_0) \quad (\text{bits/s})$$

Signal Design Problem

The continuous time and real-number interface of the AWGN channel is inconvenient for digital communications.

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- ▶ Need to convert from real numbers to a binary interface

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Discrete Time Model

An AWGN channel of bandwidth W gives rise to $2W$ independent discrete time channels per second with input-output mapping

$$Y = X + N$$

- ▶ X is a random variable with mean 0 and energy $E[X^2] \leq P/2W$
- ▶ N is Gaussian noise with 0-mean and energy $N_0/2$.
- ▶ It is customary to normalize the signal energies to joules per 2 dimensions and define

$$E_s = P/W \quad \text{Joules/2D}$$

as signal energy (per two dimensions).

- ▶ One defines the the signal-to-noise ratio as E_s/N_0 .

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Capacity

The capacity of the discrete-time AWGN channel is given by

$$C = \frac{1}{2} \log_2(1 + E_s/N_0), \quad (\text{bits}/D),$$

achieved by i.i.d. Gaussian inputs $X \sim N(0, E_s/2)$ per dimension.

Signal Design Problem

Now, we need a digital interface instead of real-valued inputs.

- ▶ Select a subset $\mathcal{A} \subset \mathcal{R}^n$ as the “signal set” or “modulation alphabet”.
- ▶ Finding a signal set with good Euclidean distance properties and other desirable features is the “signal design” problem.
- ▶ Typically, the dimension n is 1 or 2.

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Separation of coding and modulation

- ▶ Each constellation \mathcal{A} has a capacity $C_{\mathcal{A}}$ (bits/D) which is a function of E_s/N_0 .
- ▶ The spectral efficiency ρ (bits/D) has to satisfy

$$\rho < C_{\mathcal{A}}(E_s/N_0)$$

at the operating E_s/N_0 .

- ▶ The spectral efficiency is the product of two terms

$$\rho = R \times \frac{\log_2(|\mathcal{A}|)}{\dim(\mathcal{A})}$$

where R (dimensionless) is the rate of the FEC.

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Cutoff rate: A simple measure of reliability

Each constellation \mathcal{A} has a cutoff rate $R_{0,\mathcal{A}}$ (bits/D) which is a function of E_s/N_0 such that through random coding one can guarantee the existence of coding and modulation schemes with probability of frame error

$$P_e < 2^{-N[R_{0,\mathcal{A}}(E_s/N_0) - \rho]}$$

where N is the frame length in modulation symbols.

Sequential decoding and cutoff rate

- ▶ Sequential decoding (Wozencraft, 1957) is a decoding algorithm for convolutional codes that can achieve spectral efficiencies as high as the cutoff rate at constant average complexity per decoded bit.
- ▶ The difference between cutoff rate and capacity at high E_s/N_0 is less than 3 dB.
- ▶ This was regarded as the solution of the coding and modulation problem in early 70s and interest in the problem waned. (See Forney 1995 Shannon Lecture for this story.)
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M-ary Pulse Amplitude Modulation

A 1-D signal set with $\mathcal{A} = \{\pm\alpha, \pm3\alpha, \dots, \pm(M-1)\}$.

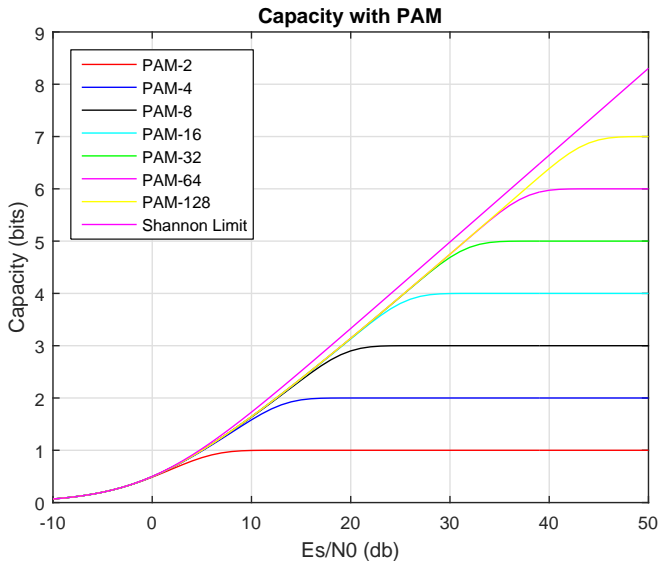
- ▶ Average energy: $E_s = 2\alpha^2(M^2 - 1)/3$ (Joules/2D)
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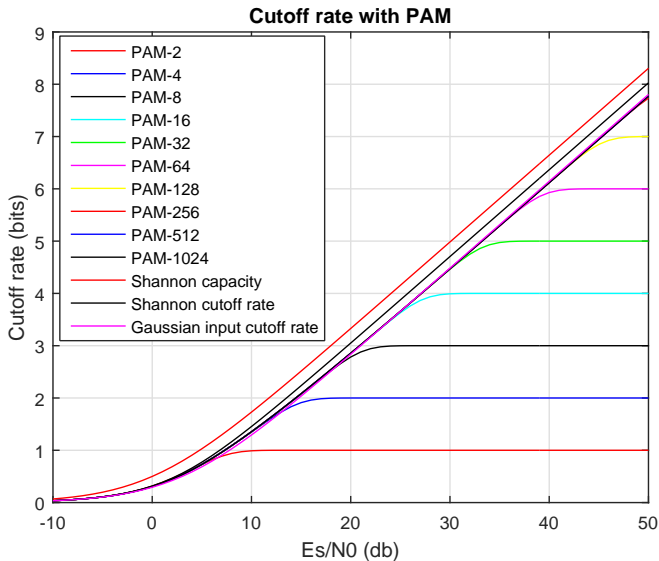
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Capacity of M -PAM



Cutoff rate of M -PAM



Conventional approach

Given a target spectral efficiency ρ and a target error rate P_e at a specific E_s/N_o ,

- ▶ select M large enough so that M -PAM capacity is close enough to the Shannon capacity at the given E_s/N_o
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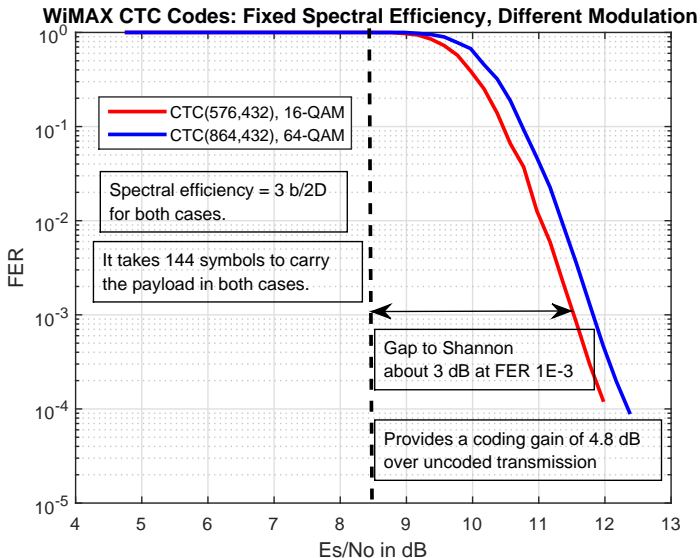
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However, with the advent of powerful codes at affordable complexity, there is a return to the conventional design methodology.

How does it work in practice?



Why change modulation instead of just the code rate?

- ▶ Suppose we fix the modulation as 64-QAM and wish to deliver data at spectral efficiencies 1, 2, 3, 4, 5 b/2D.
- ▶ We would need a coding scheme that works well at rates $1/6$, $1/3$, $1/2$, $2/3$, $5/6$.
- ▶ The inability of delivering high quality coding over a wide range of rates forces one to change the order of modulation.
- ▶ The difficulty here is practical: it is a challenge to have a coding scheme that works well over all rates from 0 to 1.

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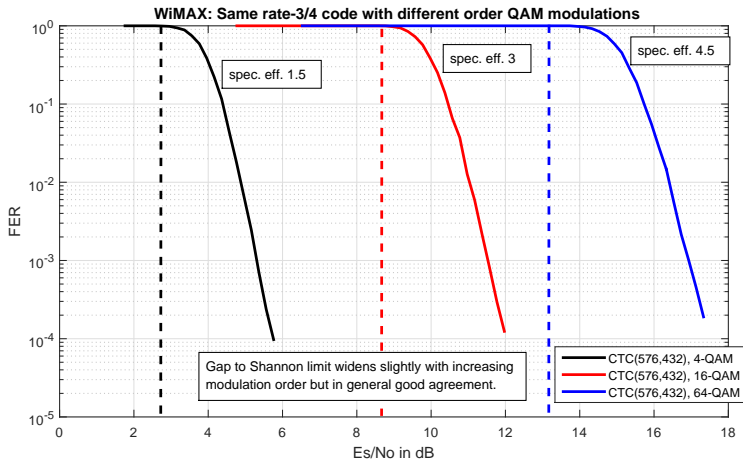
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Alternative: Fixed code, variable modulation



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Polar coding and modulation

Polar codes can be applied to modulation in at least three different ways.

- ▶ **Direct polarization**
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Direct Method

Idea: Given a system with q -ary modulation, treat it as an ordinary q -ary input memoryless channel and apply a suitable polarization transform.

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Theory of q -ary polarization exists.

- ▶ Şasoğlu, E., E. Telatar, and E. Arıkan. "Polarization for arbitrary discrete memoryless channels." IEEE ITW 2009.
- ▶ Sahebi, A. G. and S. S. Pradhan, "Multilevel polarization of polar codes over arbitrary discrete memoryless channels." IEEE Allerton, 2011.
- ▶ Park, W.-C. and A. Barg. "Polar codes for q -ary channels," IEEE Trans. Inform. Theory, 2013.
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Direct Method

The difficulty with the direct approach is complexity of decoding.

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G. Montorsi's ADBP is a promising approach for reducing the complexity here.

Multi-Level Modulation (Imai and Hirakawa, 1977)

Represent (if possible) each channel input symbol as a vector $X = (X_1, X_2, \dots, X_r)$; then the capacity can be written as a sum of capacities of smaller channels by the chain rule:

$$\begin{aligned} I(X; Y) &= I(X_1, X_2, \dots, X_r; Y) \\ &= \sum_{i=1}^r I(X_i; Y | X_1, \dots, X_{i-1}). \end{aligned}$$

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Polarization is a natural complement to MLM.

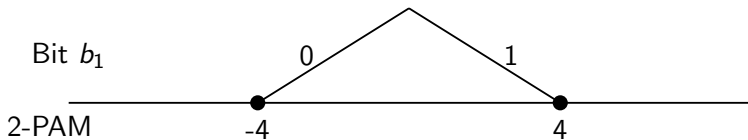
Polar coding with multi-level modulation

Already a well-studied subject:

- ▶ Arıkan, E., “Polar Coding,” Plenary Talk, ISIT 2011.
- ▶ Seidl, M., Schenk, A., Stierstorfer, C., and Huber, J. B. “Polar-coded modulation,” IEEE Trans. Comm. 2013.
- ▶ Seidl, M., Schenk, A., Stierstorfer, C., and Huber, J. B. “Multilevel polar-coded modulation’,” IEEE ISIT 2013
- ▶ Ionita, Corina, et al. ”On the design of binary polar codes for high-order modulation.” IEEE GLOBECOM, 2014.
- ▶ Beygi, L., Agrell, E., Kahn, J. M., and Karlsson, M., “Coded modulation for fiber-optic networks,” IEEE Sig. Proc. Mag., 2014.
- ▶ ...

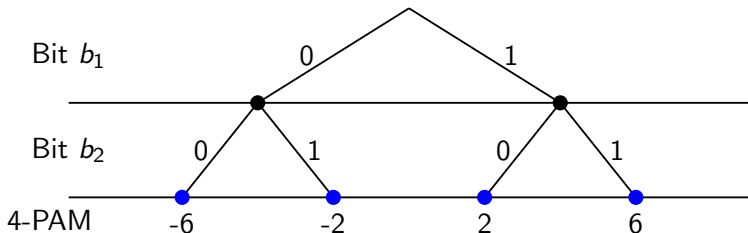
Example: 8-PAM as 3 bit channels

- ▶ PAM signals selected by three bits (b_1, b_2, b_3)
- ▶ Three layers of binary channels created
- ▶ Each layer encoded independently
- ▶ Layers decoded in the order b_3, b_2, b_1



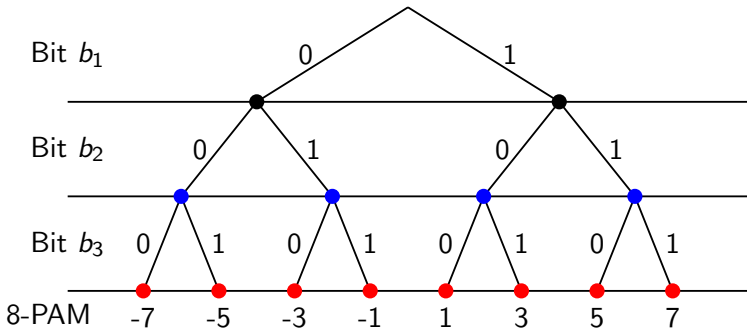
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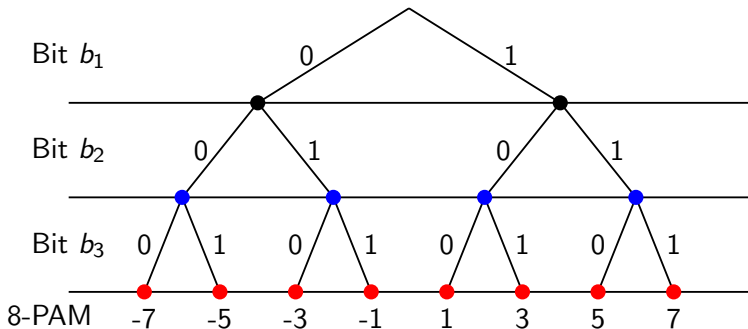
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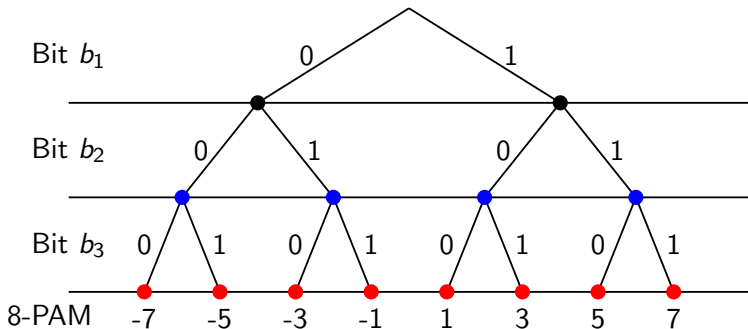
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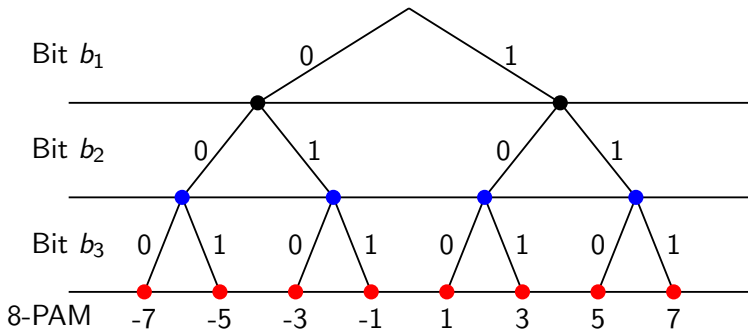
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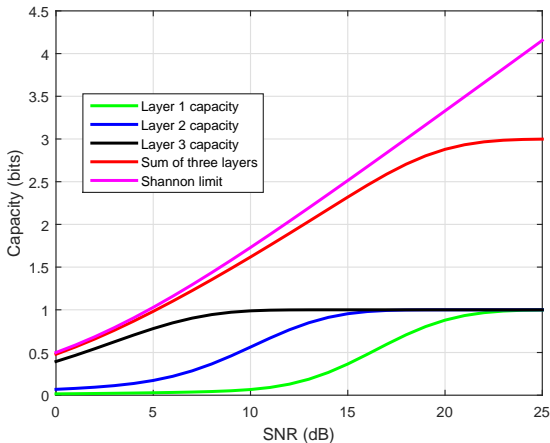


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Polarization across layers by natural labeling



Most coding work needs to be done at the least significant bits.

Lattices and polar coding

Yan, Cong, and Liu explored the connection between lattices and polar coding.

- ▶ Yan, Yanfei, and L. Cong, “A construction of lattices from polar codes.” IEEE 2012 ITW.
- ▶ Yan, Yanfei, Ling Liu, Cong Ling, and Xiaofu Wu. “Construction of capacity-achieving lattice codes: Polar lattices.” arXiv preprint arXiv:1411.0187 (2014)

Lattices and polar coding

Yan *et al* used the Barnes-Wall lattice constructions such as

$$BW_{16} = RM(1, 4) + 2RM(3, 4) + 4(\mathbb{Z}^{16})$$

as a template for constructing polar lattices of the type

$$P_{16} = P(1, 4) + 2P(3, 4) + 4(\mathbb{Z}^{16})$$

and demonstrated by simulations that polar lattices perform better.

BICM

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As in MLM, BICM splits the channel input symbols into a vector $X = (X_1, X_2, \dots, X_r)$ but strives to do so such that

$$\begin{aligned} I(X; Y) &= I(X_1, X_2, \dots, X_r; Y) \\ &= \sum_{i=1}^r I(X_i; Y | X_1, \dots, X_{i-1}) \\ &\approx \sum_{i=1}^r I(X_i; Y). \end{aligned}$$

BICM vs Multi Level Modulation

Why has BICM won over MLM and other techniques in practice?

- ▶ MLM is provably capacity-achieving; BICM is suboptimal but the rate penalty is tolerable.
- ▶ MLM has to do delicate rate-matching at individual layers, which is difficult with turbo and LDPC codes.
- ▶ BICM is well-matched to iterative decoding methods used with turbo and LDPC codes.
- ▶ MLM suffers extra latency due to multi-stage decoding (mitigated in part by the lack of need for protecting the upper layers by long codes)
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- ▶ MLM is provably capacity-achieving; BICM is suboptimal but the rate penalty is tolerable.
- ▶ MLM has to do delicate rate-matching at individual layers, which is difficult with turbo and LDPC codes.
- ▶ BICM is well-matched to iterative decoding methods used with turbo and LDPC codes.
- ▶ MLM suffers extra latency due to multi-stage decoding (mitigated in part by the lack of need for protecting the upper layers by long codes)
- ▶ With MLM, the overall code is split into shorter codes which weakens performance (one may mix and match the block lengths of each layer to alleviate this problem).

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BICM and Polar Coding

This subject, too, has been studied in connection with polar codes.

- ▶ MahdaviFar, H. and El-Khamy, M. and Lee, J. and Kang, I., “Polar Coding for Bit-Interleaved Coded Modulation,” IEEE Trans. Veh. Tech., 2015.
- ▶ Afser, H., N. Tirpan, H. Delic, and M. Koca, “Bit-interleaved polar-coded modulation,” Proc. IEEE WCNC, 2014.
- ▶ Chen, Kai, Kai Niu, and Jia-Ru Lin. “An efficient design of bit-interleaved polar coded modulation.” IEEE PIMRC 2013.
- ▶ ...

Thank you!

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