



April 27, 2017

MASTER'S THESIS
for
Student's name
Student ID 0815, Degree EI

Thesis Title

Problem description:

Expert knowledge is already required to teach robotic systems how to grasp an object, which is seen as a rather simple task for humans [1].

Tasks:

- Literature research
- Task2, :

Bibliography:

[1] O. Khatib, K. Yokoi, K. Chang, D. Ruspini, R. Holmberg, A. Casal, and A. Baader. Force strategies for cooperative tasks in multiple mobile manipulation systems. In *Robotics Research*, pages 333–342. Springer London, 1996.

Supervisor: Dipl.-Ing./ M. Sc. Your Name
Start: XX.XX.2015
Intermediate Report: XX.XX.2015
Delivery: XX.XX.2015

(D. Lee)
Univ.-Professor