# Generation of Interactive Benchmark for Motion Planning of Autonomous Vehicles

# Background

CommonRoad[1] is a collection of composable benchmarks for motion planning on roads, and provides researchers with a means of evaluating and comparing their motion planners for autonomous vehicles. An exemplary scenario created from the data recorded in the city center of Munich (Stachus) is shown below:



Visualization of an exemplary scenario from Stachus using CommonRoad.

However, currently CommonRoad only provides pre-recorded scenarios, i.e. the other traffic participants in the scenario are **non-interactive** and their behaviours do not change with regard to the action of the ego vehicle. This disadvantage could be overcome by integrating CommonRoad with SUMO [2] - an urban mobility simulator. An artificial traffic scenario generated by SUMO is shown below:



An example of SUMO scenario.

# Description

The aim of this thesis is to elevate the impact and influence of CommonRoad by creating a **interactive** benchmark for motion planning of autonomous vehicles. A raw idea of its working mechanism is as follows:

- 1. Establish correspondence between CommonRoad and SUMO by converting Common-Road road networks to SUMO road networks using existing converter.
- 2. Establish connection between CommonRoad and SUMO using existing CommonRoad-SUMO interface.
- 3. Generate reactive behaviors of other traffic participants in SUMO based on ego vehicle's action in every time step, and update the states of corresponding traffic participants



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## Supervisor:

Prof. Dr.-Ing. Matthias Althoff

## Advisor:

Edmond Irani Liu, M.Sc.

## Research project:

**Type:** Bachelor/Master's thesis

Research area: Benchmark Creation, Autonomous Vehicles

**Programming language:** C++, Python

### **Required skills:**

Good programming skill in both C++ and Python; Optional: knowledge of Docker

Language: English

Date of submission: August 29, 2019

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www6.in.tum.de/people/edmondirani-liu-msc in CommonRoad.

- 4. Generate a bunch of interactive scenarios with deterministic parameters to guarantee reproducibility, and attach necessary elements (scenario ID, planning problems, cost functions, etc.) to form the benchmark.
- 5. Deploy identical environment on the Chair's server to reproduce the scenario in planning phase , and evaluate uploaded solutions to scenarios.

# Tasks

- Familiarize with CommonRoad toolkit
- Familiarize with SUMO
- Familiarize with CommonRoad-SUMO interface
- Generate interactive scenarios as mentioned above, and finally produce a benchmark
- Deploy a running environment to the Chair's server
- Evaluate uploaded solutions based on given cost functions

# References

- [1] Commonroad. https://commonroad.in.tum.de/.
- [2] Sumo. https://sumo.dlr.de/wiki/Simulation\_of\_Urban\_MObility\_-\_Wiki/.



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